Scribed by Haaris Khan Last modified 10/3/2017

### Lecture 5

In which we study the SDP relaxation of Max Cut in random graphs.

# 1 Quick Review of Chernoff Bounds

Suppose  $X_1, ..., X_n$  are mutually independent random variables with values 0, 1. Let  $X := \sum_{i=1}^{n} X_i$ . The Chernoff Bounds claim the following:

1.  $\forall \epsilon \text{ such that } 0 \leq \epsilon \leq 1$ ,

$$\mathbb{P}(|X - \mathbb{E}[X]|) > \epsilon \cdot \mathbb{E}[X]) \le \exp(\Omega(\epsilon^2 \cdot \mathbb{E}[X]))$$

2.  $\forall t > 1$ ,

$$\mathbb{P}(|X - \mathbb{E}[X]| \ge t \cdot \mathbb{E}[X]) \le \exp(-\Omega((t\log(t)) \cdot \mathbb{E}[X]))$$

3. When we do not know  $\mathbb{E}[X]$ , we can bound as follows:

 $\mathbb{P}(|X - \mathbb{E}[X]| \ge \epsilon \cdot n) \le \exp(-\Omega(\epsilon^2 \cdot n))$ 

# 2 Cutting a Near-Optimal Number of Edges in $G_{n,p}$ Via SDP Rounding

Consider  $G_{n,p}$  where  $p > \frac{\log(n)}{n}$ . We show that with 1 - o(1) probability, the max-degree will be O(d)

- Fix v
- For some constant c,

 $\mathbb{P}$ 

$$\begin{aligned} (\text{v has degree} > c \cdot d) &= \mathbb{P}(|deg(v) - \mathbb{E}[v]| > (c-1) \mathbb{E}[deg(v)]) \\ &\leq \exp(-\Omega((c-1)\log(c-1) \cdot d)) \text{ (by Chernoff Bounds)} \\ &\leq \exp(-\Omega((c-1)\log(c-1) \cdot \log(n))) \\ &\leq \frac{1}{n^2}, \text{ for some choice of constant c} \end{aligned}$$

So  $\mathbb{P}(\exists v \text{ with degree } > c \cdot d) \le n \cdot \frac{1}{n^2} \le \frac{1}{n}$ 

Next, we compute the number of vertices that participate in a triangle. Recall that degree d can be bounded by  $o(n^{\frac{1}{3}})$ 

 $\mathbb{E}[\text{number vertices in triangles}] = n \cdot \mathbb{P}(\text{v participates in a triangle})$ 

If a vertex participates in a triangle, there are  $\binom{n-1}{2}$  ways of choosing the other two vertices that participate with v in the triangle.

So the expected number of vertices in triangles can be bounded by

$$\mathbb{E}[\text{number vertices in triangles}] \le n \cdot p^3 \cdot \binom{n-1}{2}$$
$$\le n^3 \cdot p^3$$
$$= o(n) \text{ if } p = o\left(\frac{1}{n^{\frac{2}{3}}}\right), \ d = o(n^{\frac{1}{3}})$$

So with o(1) probability,

- All vertices have degree O(d)
- o(n) vertices participate in triangles.

#### 3 Eigenvalue Computations and SDP

Problems like finding the largest / smallest eigenvalue can be solved using SDP Let M be symmetric,  $\lambda_{\max}$  be the largest eigenvalue of M:  $\lambda_{\max} = \max_x \frac{\boldsymbol{x}^T M \boldsymbol{x}}{\|\boldsymbol{x}\|^2}$  We can formulate this as Quadratic Programming:

$$\max_{i,j} \sum_{i,j} M_{i,j} x_i y_j \text{s.t.}$$
$$\sum_i x_i^2 = 1$$

We showed previously that we can relax a Quadratic Program to SDP:

$$\begin{split} \max_{i,j} & \sum_{i,j} M_{i,j} \langle \boldsymbol{x_i}, \boldsymbol{x_j} \rangle \text{s.t} \\ & \sum_i \|\boldsymbol{x_i}\|^2 = 1 \end{split}$$

In fact, it happens that these two are equivalent. To show this, we must show that a vector solution x of SDP can hold as a solution to the QP and vice versa.

Proving x for QP is valid for SDP: Trivial. Any solution x to our Quadratic Program must be a solution for our SDP since it is a relaxation of the problem; then the optimum of our QP must be less than or equal to the optimum of our SDP

Proving x for SDP is valid for QP: Consider x := vector solution of cost c. We note that our SDP can be transformed into an unconstrained optimization problem as follows:

$$\max_{i,j} \quad \frac{\sum_{i,j} M_{i,j} \langle \boldsymbol{x_i}, \boldsymbol{x_j} \rangle}{\sum_i \|\boldsymbol{x_i}\|^2}$$

The cost c can be defined as the value of our solution:

$$c = \frac{\sum_{i,j} M_{i,j} \sum_{k} \boldsymbol{x_{k}}^{i} \boldsymbol{x_{k}}^{j}}{\sum_{i} \sum_{k} \|\boldsymbol{x_{k}}^{i}\|^{2}}$$
$$\leq \max_{k} \frac{\sum_{i,j} M_{i,j} \boldsymbol{x_{k}}^{i} \boldsymbol{x_{k}}^{j}}{\sum_{i} \|\boldsymbol{x_{k}}^{i}\|^{2}}$$

We get a one-dimensional solution when we use the  $k^{th}$  element of x, and wish to find the k that maximizes this.

We use the following inequality:

$$\frac{a_1+\ldots+a_m}{b_1+\ldots+b_m} \leq \max_{k=1,\ldots,m} \frac{a_k}{b_k}, b_k > 0$$

Proof:

$$\sum_{i} a_{i} = \sum_{i} b_{i} \cdot \frac{a_{i}}{b_{i}} \le \sum_{i} b_{i} \cdot \max_{k} \frac{a_{k}}{b_{k}}$$
$$= \max_{k} \frac{a_{k}}{b_{k}} \cdot \sum_{i} b_{i}$$

## 4 SDP Max-Cut: Spectral Norm as a SDP Certificate

Consider the SDP relaxation of Max-Cut on Graph G:

max 
$$\sum_{(i,j)\in E} \frac{1}{4} \|\boldsymbol{X}_{i} - \boldsymbol{X}_{j}\|^{2}$$
s.t. 
$$\forall v \in V, \|\boldsymbol{X}_{v}^{2}\| = 1$$

Let the optimum value for this SDP be SDPMaxCut(G). It's obvious that  $MaxCut(G) \leq SDPMaxCut(G)$ . Under our constraints, we can rewrite our SDP as

$$\sum_{(i,j)\in E}\frac{1}{2}-\frac{1}{2}\langle \pmb{X_i},\pmb{X_j}\rangle$$

So our new optimization problem is

$$\max \qquad \frac{|E|}{2} - \sum_{(i,j)\in E} \frac{1}{2} \langle \mathbf{X}_i, \mathbf{X}_j \rangle$$
  
s.t.  
$$\forall i \in V, \|\mathbf{X}_i\|^2 = 1$$

We can relax our constraint to the following:  $\forall i \in V, \sum_i ||\mathbf{X}_i||^2 = n$ . Relaxing our constraint will yield an optimization problem with a solution less than the stricter constraint (call this SDP'MaxCut(G)):

$$\begin{split} \max &\quad \frac{|E|}{2} - \sum_{(i,j) \in E} \frac{1}{2} \langle \boldsymbol{X_i}, \boldsymbol{X_j} \rangle \\ \text{s.t.} &\quad \\ &\quad \sum_{v} \|\boldsymbol{X_v}\|^2 = n \end{split}$$

Clearly, we have the following inequalities:  $MaxCut(G) \leq SDPMaxCut(G) \leq SDP'MaxCut(G)$ . We can rewrite SDP'MaxCut(G) as

$$\max \quad \frac{|E|}{2} + \frac{n}{4} \cdot \sum_{i,j} \frac{-A_{i,j} \langle \mathbf{X}_i, \mathbf{X}_j \rangle}{\sum_i \|\mathbf{X}_i\|^2}$$
$$\sum_v \|\mathbf{X}_v\|^2 = n$$

Note that our objective function computes the largest eigenvalue of -A:

$$=\frac{|E|}{2}+\frac{n}{4}\cdot\lambda_{\max}(-A)$$

For every graph  $G_{n,p}$  with  $0 \le p \le 1$ ,

$$MaxCut(G) \le SDPMaxCut(G) \le \frac{|E|}{2} + \frac{n}{4} \cdot \lambda_{\max}(-A)$$

$$\leq \frac{|E|}{2} + \frac{n}{4} \cdot \lambda_{\max}(pJ - A)$$
$$\leq \frac{|E|}{2} + \frac{n}{4} \cdot \|pJ - A\|$$

Recall from previous lectures that for  $p > \frac{\log(n)}{n}$ , the adjacency matrix of A sampled from  $G_{n,p}$  has  $\|pJ - A\| \le O(\sqrt{np})$  with high probability. This implies that  $SDPMaxCut(G) \le \frac{|E|}{2} + O(n \cdot \sqrt{d})$ . Semantically, this means that SDPMaxCut(G) computes in poly-time a correct upper-bound of MaxCut(G).

#### 5 Trace and Eigenvalues

Suppose matrix M is symmetric with eigenvalues  $\lambda_1 \dots \lambda_n$ . The following are true:

- $M^k$  eigenvalues are  $\lambda_1^k \dots \lambda_n^k$
- $trace(M) := \sum_{i,i} M_{i,i}$ ;  $trace(M) = \sum_i \lambda_i$

Then, for  $M^{2k}$ ,  $trace(M^{2k}) = \lambda_1^{2k} + \ldots + \lambda_n^{2k}$ .

$$(\max_{i} |\lambda_i|)^{2k} \le trace(M^{2k}) \le n \cdot (\max_{i} |\lambda_i|)^{2k}$$

Also,

$$\|M\| \le (trace(M^{2k})^{\frac{1}{2k}} \le n^{\frac{1}{2k}} \cdot \|M\|$$

 $A_{i,j}$  is defined as the number of expected paths from *i* to *j* that take *k* steps (not necessarily simple paths in a graph)

 $=\sum_{\text{paths from i to j}} M_{i,a_1} \dots M_{a_n,j}$ 

Our goal with this is to compute the eigenvalues  $\lambda$ . Since traces relates the sum of the diagonal and the sum of eigenvalues for symmetric M, we can use this to provide an upper bound for symmetric M.