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## Lecture 5

In which we study the SDP relaxation of Max Cut in random graphs.

## 1 Quick Review of Chernoff Bounds

Suppose $X_{1}, \ldots, X_{n}$ are mutually independent random variables with values 0,1 . Let $X:=\sum_{i=1}^{n} X_{i}$. The Chernoff Bounds claim the following:

1. $\forall \epsilon$ such that $0 \leq \epsilon \leq 1$,

$$
\mathbb{P}(|X-\mathbb{E}[X]|)>\epsilon \cdot \mathbb{E}[X]) \leq \exp \left(\Omega\left(\epsilon^{2} \cdot \mathbb{E}[X]\right)\right)
$$

2. $\forall t>1$,

$$
\mathbb{P}(|X-\mathbb{E}[X]| \geq t \cdot \mathbb{E}[X]) \leq \exp (-\Omega((t \log (t)) \cdot \mathbb{E}[X]))
$$

3. When we do not know $\mathbb{E}[X]$, we can bound as follows:

$$
\mathbb{P}(|X-\mathbb{E}[X]| \geq \epsilon \cdot n) \leq \exp \left(-\Omega\left(\epsilon^{2} \cdot n\right)\right)
$$

## 2 Cutting a Near-Optimal Number of Edges in $G_{n, p}$ Via SDP Rounding

Consider $G_{n, p}$ where $p>\frac{\log (n)}{n}$. We show that with $1-o(1)$ probability, the max-degree will be $O(d)$

- Fix v
- For some constant c,

$$
\begin{aligned}
& \mathbb{P}(\mathrm{v} \text { has degree }>c \cdot d)=\mathbb{P}(|\operatorname{deg}(v)-\mathbb{E}[v]|>(c-1) \mathbb{E}[\operatorname{deg}(v)]) \\
& \leq \exp (-\Omega((c-1) \log (c-1) \cdot d))(\text { by Chernoff Bounds }) \\
& \leq \exp (-\Omega((c-1) \log (c-1) \cdot \log (n)) \\
& \leq \frac{1}{n^{2}}, \text { for some choice of constant } \mathrm{c}
\end{aligned}
$$

So $\mathbb{P}(\exists v$ with degree $>c \cdot d) \leq n \cdot \frac{1}{n^{2}} \leq \frac{1}{n}$
Next, we compute the number of vertices that participate in a triangle. Recall that degree $d$ can be bounded by $o\left(n^{\frac{1}{3}}\right)$

$$
\mathbb{E}[\text { number vertices in triangles }]=n \cdot \mathbb{P}(\mathrm{v} \text { participates in a triangle })
$$

If a vertex participates in a triangle, there are $\binom{n-1}{2}$ ways of choosing the other two vertices that participate with v in the triangle.
So the expected number of vertices in triangles can be bounded by

$$
\begin{gathered}
\mathbb{E}[\text { number vertices in triangles }] \leq n \cdot p^{3} \cdot\binom{n-1}{2} \\
\leq n^{3} \cdot p^{3} \\
=o(n) \text { if } p=o\left(\frac{1}{n^{\frac{2}{3}}}\right), d=o\left(n^{\frac{1}{3}}\right)
\end{gathered}
$$

So with $o(1)$ probability,

- All vertices have degree $O(d)$
- $o(n)$ vertices participate in triangles.


## 3 Eigenvalue Computations and SDP

Problems like finding the largest / smallest eigenvalue can be solved using SDP
Let $M$ be symmetric, $\lambda_{\max }$ be the largest eigenvalue of $\mathrm{M}: \lambda_{\max }=\max _{x} \frac{x^{T} M x}{\|x\|^{2}}$ We can formulate this as Quadratic Programming:

$$
\begin{aligned}
\max _{i, j} & \sum_{i, j} M_{i, j} x_{i} y_{j} \mathrm{s.t.} \\
& \sum_{i} x_{i}^{2}=1
\end{aligned}
$$

We showed previously that we can relax a Quadratic Program to SDP:

$$
\begin{aligned}
\max _{i, j} & \sum_{i, j} M_{i, j}\left\langle\boldsymbol{x}_{\boldsymbol{i}}, \boldsymbol{x}_{\boldsymbol{j}}\right\rangle \mathrm{s.t.} \\
& \sum_{i}\left\|\boldsymbol{x}_{\boldsymbol{i}}\right\|^{2}=1
\end{aligned}
$$

In fact, it happens that these two are equivalent. To show this, we must show that a vector solution $x$ of SDP can hold as a solution to the QP and vice versa.
Proving $x$ for QP is valid for SDP: Trivial. Any solution $x$ to our Quadratic Program must be a solution for our SDP since it is a relaxation of the problem; then the optimum of our QP must be less than or equal to the optimum of our SDP
Proving $x$ for SDP is valid for QP: Consider $x:=$ vector solution of cost c . We note that our SDP can be transformed into an unconstrained optimization problem as follows:

$$
\max _{i, j} \frac{\sum_{i, j} M_{i, j}\left\langle\boldsymbol{x}_{i}, \boldsymbol{x}_{\boldsymbol{j}}\right\rangle}{\sum_{i}\left\|\boldsymbol{x}_{\boldsymbol{i}}\right\|^{2}}
$$

The cost c can be defined as the value of our solution:

$$
\begin{aligned}
c & =\frac{\sum_{i, j} M_{i, j} \sum_{k} \boldsymbol{x}_{\boldsymbol{k}}{ }^{i} \boldsymbol{x}_{\boldsymbol{k}}{ }^{j}}{\sum_{i} \sum_{k} \|\left.\boldsymbol{x}_{\boldsymbol{k}}{ }^{i}\right|^{2}} \\
& \leq \max _{k} \frac{\sum_{i, j} M_{i, j} \boldsymbol{x}_{\boldsymbol{k}}{ }^{i} \boldsymbol{x}_{\boldsymbol{k}}{ }^{j}}{\sum_{i}\left\|\boldsymbol{x}_{\boldsymbol{k}}{ }^{i}\right\|^{2}}
\end{aligned}
$$

We get a one-dimensional solution when we use the $k^{\text {th }}$ element of $x$, and wish to find the $k$ that maximizes this.
We use the following inequality:

$$
\frac{a_{1}+\ldots+a_{m}}{b_{1}+\ldots+b_{m}} \leq \max _{k=1, \ldots, m} \frac{a_{k}}{b_{k}}, b_{k}>0
$$

Proof:

$$
\begin{aligned}
\sum_{i} a_{i}= & \sum_{i} b_{i} \cdot \frac{a_{i}}{b_{i}} \leq \sum_{i} b_{i} \cdot \max _{k} \frac{a_{k}}{b_{k}} \\
& =\max _{k} \frac{a_{k}}{b_{k}} \cdot \sum_{i} b_{i}
\end{aligned}
$$

## 4 SDP Max-Cut: Spectral Norm as a SDP Certificate

Consider the SDP relaxation of Max-Cut on Graph $G$ :

$$
\begin{array}{ll}
\max & \sum_{(i, j) \in E} \frac{1}{4}\left\|\boldsymbol{X}_{\boldsymbol{i}}-\boldsymbol{X}_{\boldsymbol{j}}\right\|^{2} \\
\text { s.t. } & \forall v \in V,\left\|\boldsymbol{X}_{\boldsymbol{v}}{ }^{2}\right\|=1
\end{array}
$$

Let the optimum value for this SDP be $S D P M a x C u t(G)$. It's obvious that $\operatorname{MaxCut}(G) \leq$ $S D P M a x C u t(G)$. Under our constraints, we can rewrite our SDP as

$$
\sum_{(i, j) \in E} \frac{1}{2}-\frac{1}{2}\left\langle\boldsymbol{X}_{\boldsymbol{i}}, \boldsymbol{X}_{\boldsymbol{j}}\right\rangle
$$

So our new optimization problem is

$$
\begin{array}{ll}
\max & \frac{|E|}{2}-\sum_{(i, j) \in E} \frac{1}{2}\left\langle\boldsymbol{X}_{\boldsymbol{i}}, \boldsymbol{X}_{\boldsymbol{j}}\right\rangle \\
\text { s.t. } & \forall i \in V,\left\|\boldsymbol{X}_{\boldsymbol{i}}\right\|^{2}=1
\end{array}
$$

We can relax our constraint to the following: $\forall i \in V, \sum_{i}\left\|\boldsymbol{X}_{i}\right\|^{2}=n$. Relaxing our constraint will yield an optimization problem with a solution less than the stricter constraint (call this SDP $\left.P^{\prime} \operatorname{MaxCut}(G)\right)$ :

$$
\begin{array}{ll}
\max & \frac{|E|}{2}-\sum_{(i, j) \in E} \frac{1}{2}\left\langle\boldsymbol{X}_{\boldsymbol{i}}, \boldsymbol{X}_{\boldsymbol{j}}\right\rangle \\
\text { s.t. } & \\
& \sum_{v}\left\|\boldsymbol{X}_{\boldsymbol{v}}\right\|^{2}=n
\end{array}
$$

Clearly, we have the following inequalities: $\operatorname{MaxCut}(G) \leq S D P M a x C u t(G) \leq S D P^{\prime} \operatorname{MaxCut}(G)$. We can rewrite $S D P^{\prime} \operatorname{MaxCut}(G)$ as

$$
\begin{array}{ll}
\max & \frac{|E|}{2}+\frac{n}{4} \cdot \sum_{i, j} \frac{-A_{i, j}\left\langle\boldsymbol{X}_{\boldsymbol{i}}, \boldsymbol{X}_{\boldsymbol{j}}\right\rangle}{\sum_{i}\left\|\boldsymbol{X}_{\boldsymbol{i}}\right\|^{2}} \\
& \sum_{v}\left\|\boldsymbol{X}_{\boldsymbol{v}}\right\|^{2}=n
\end{array}
$$

Note that our objective function computes the largest eigenvalue of $-A$ :

$$
=\frac{|E|}{2}+\frac{n}{4} \cdot \lambda_{\max }(-A)
$$

For every graph $G_{n, p}$ with $0 \leq p \leq 1$,

$$
\operatorname{MaxCut}(G) \leq S D P M a x C u t(G) \leq \frac{|E|}{2}+\frac{n}{4} \cdot \lambda_{\max }(-A)
$$

$$
\begin{aligned}
\leq & \frac{|E|}{2}+\frac{n}{4} \cdot \lambda_{\max }(p J-A) \\
& \leq \frac{|E|}{2}+\frac{n}{4} \cdot\|p J-A\|
\end{aligned}
$$

Recall from previous lectures that for $p>\frac{\log (n)}{n}$, the adjacency matrix of $A$ sampled from $G_{n, p}$ has $\|p J-A\| \leq O(\sqrt{n p})$ with high probability. This implies that $S D P M a x C u t(G) \leq$ $\frac{|E|}{2}+O(n \cdot \sqrt{d})$. Semantically, this means that $S D P M a x C u t(G)$ computes in poly-time a correct upper-bound of $\operatorname{MaxCut}(G)$.

## 5 Trace and Eigenvalues

Suppose matrix $M$ is symmetric with eigenvalues $\lambda_{1} \ldots \lambda_{n}$. The following are true:

- $M^{k}$ eigenvalues are $\lambda_{1}^{k} \ldots \lambda_{n}^{k}$
- $\operatorname{trace}(M):=\sum_{i, i} M_{i, i} ; \operatorname{trace}(M)=\sum_{i} \lambda_{i}$

Then, for $M^{2 k}, \operatorname{trace}\left(M^{2 k}\right)=\lambda_{1}^{2 k}+\ldots+\lambda_{n}^{2 k}$.

$$
\left(\max _{i}\left|\lambda_{i}\right|\right)^{2 k} \leq \operatorname{trace}\left(M^{2 k}\right) \leq n \cdot\left(\max _{i}\left|\lambda_{i}\right|\right)^{2 k}
$$

Also,

$$
\|M\| \leq\left(\operatorname{trace}\left(M^{2 k}\right)^{\frac{1}{2 k}} \leq n^{\frac{1}{2 k}} \cdot\|M\|\right.
$$

$A_{i, j}$ is defined as the number of expected paths from $i$ to $j$ that take $k$ steps (not necessarily simple paths in a graph)
$=\sum_{\text {paths from ito j }} M_{i, a_{1}} \ldots M_{a_{n}, j}$
Our goal with this is to compute the eigenvalues $\lambda$. Since traces relates the sum of the diagonal and the sum of eigenvalues for symmetric $M$, we can use this to provide an upper bound for symmetric $M$.

